

Avalanche-size statistics in a Burridge-Knopoff type spring-block model



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Aims:

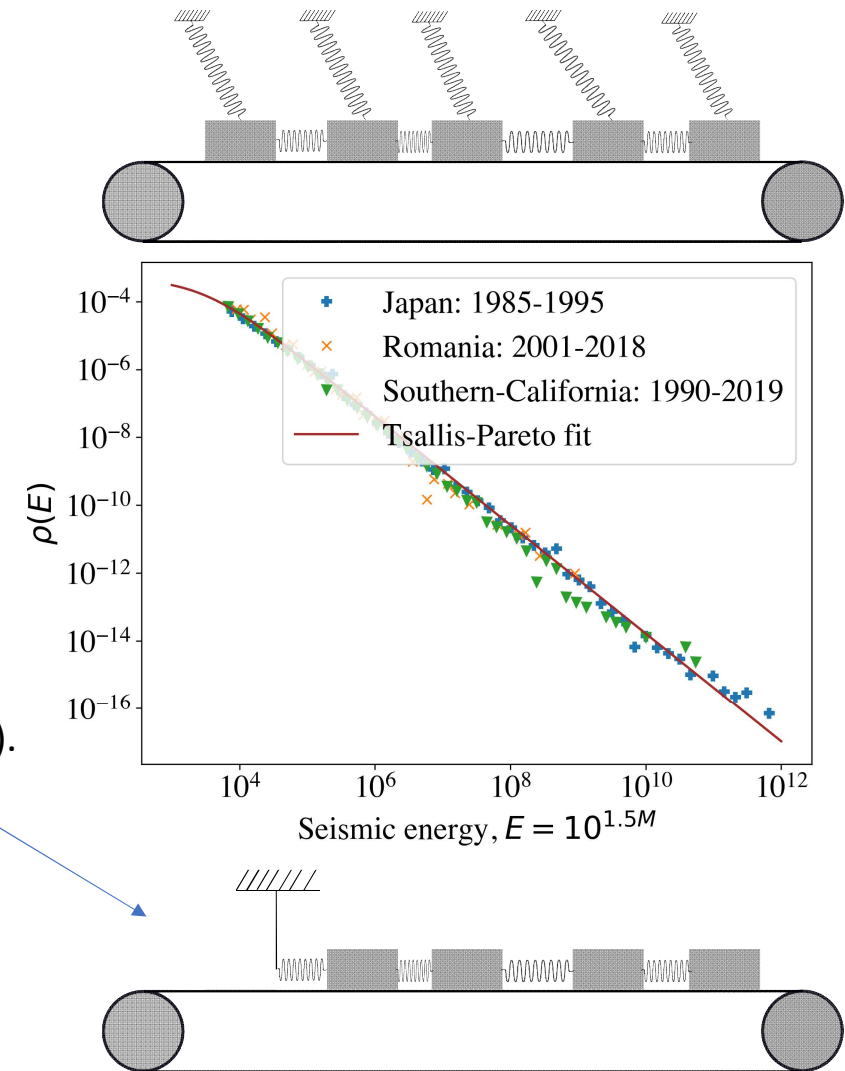
- Development of a treadmill-based setup for the experimental study of the Burridge-Knopoff type spring-block system
- Studying the system to find interesting dynamics (avalanches,...)
- Reproduction of the observed behaviors using a simple computational model

Similar study:

- B. Sándor, F. Járαι-Szabó, T. Tél and Z. Néda, Phys. Rev. E 87, 042920 (2013).

Interesting chaotic, periodic and quasiperiodic behaviors

- Varamashvili, Nodar, et al. "Mass-movement and seismic processes study using Burridge-Knopoff laboratory and mathematical models." *JOURNAL OF THE GEORGIAN GEOPHYSICAL SOCIETY* 18.18 (2015).

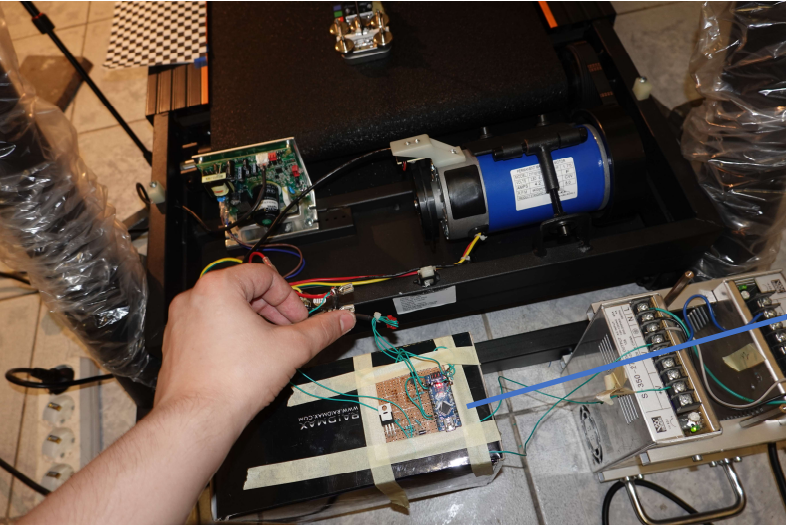


Experimental setup

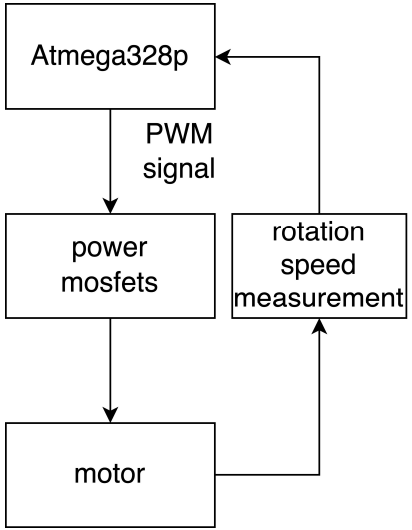
Treadmill with blocks and springs



Treadmill speed controller



controller block diagram



snapshot of the dynamics

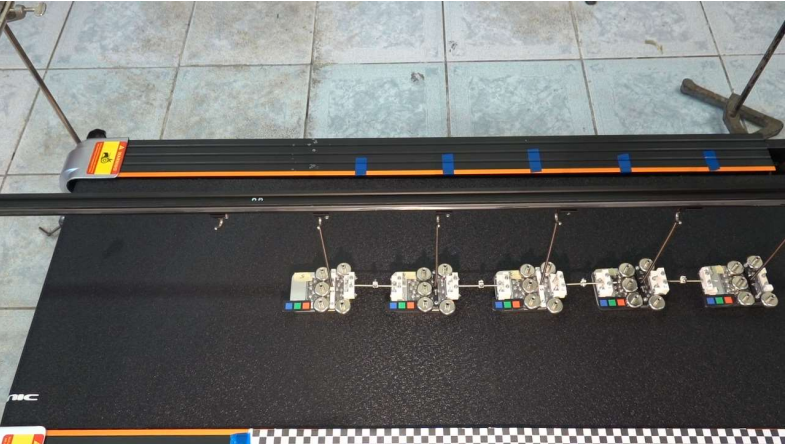
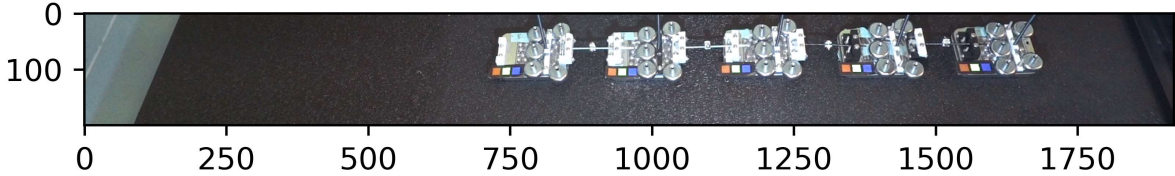
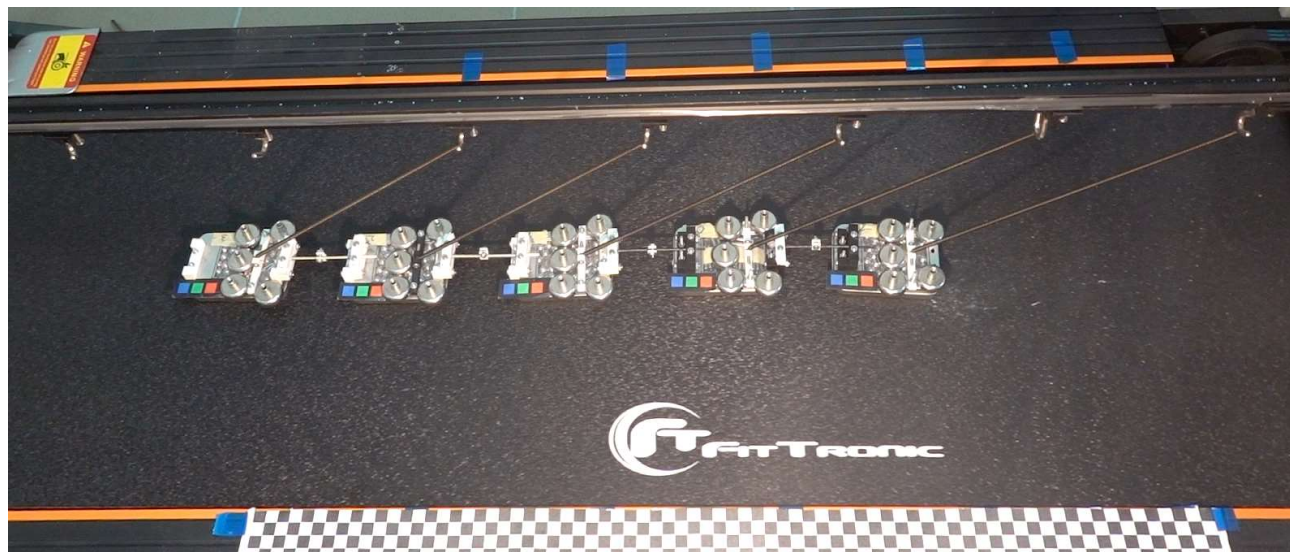


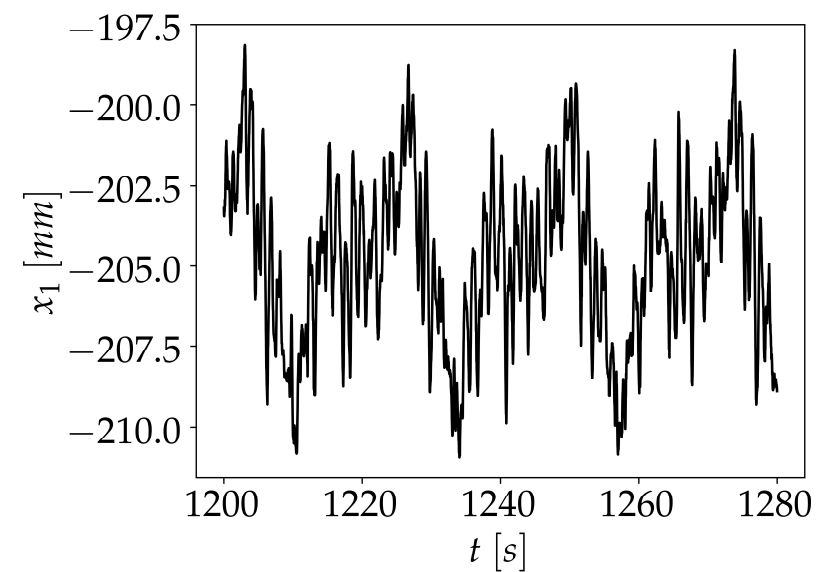
image processing algorithm to locate the blocks



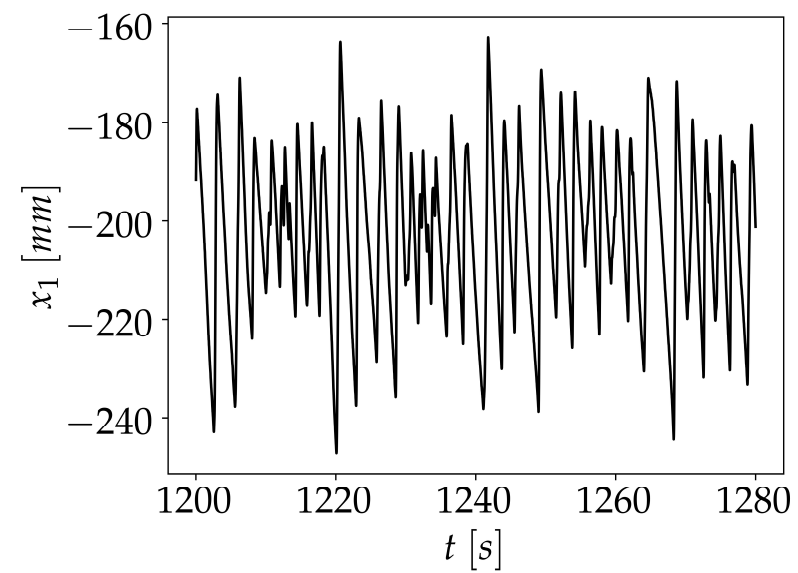
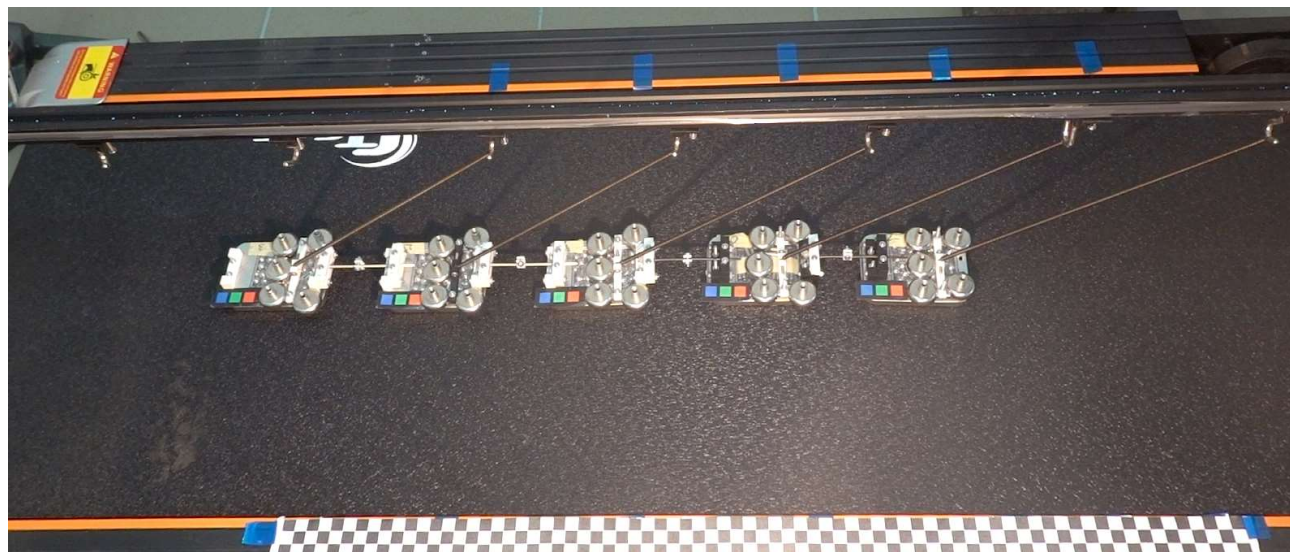
quasi-periodic behavior -> $v=0.4\text{km/h}$



The position of the first block



Stick-Slip behavior (avalanches) -> $v=0.1\text{km/h}$



Avalanche definition

- Consecutive time steps where the kinetic energy of the blocks increases
- The energy of the avalanche is the difference between the initial and final kinetic energies of the blocks

Implementation:

- Identification of the i -th local minimum in kinetic energy

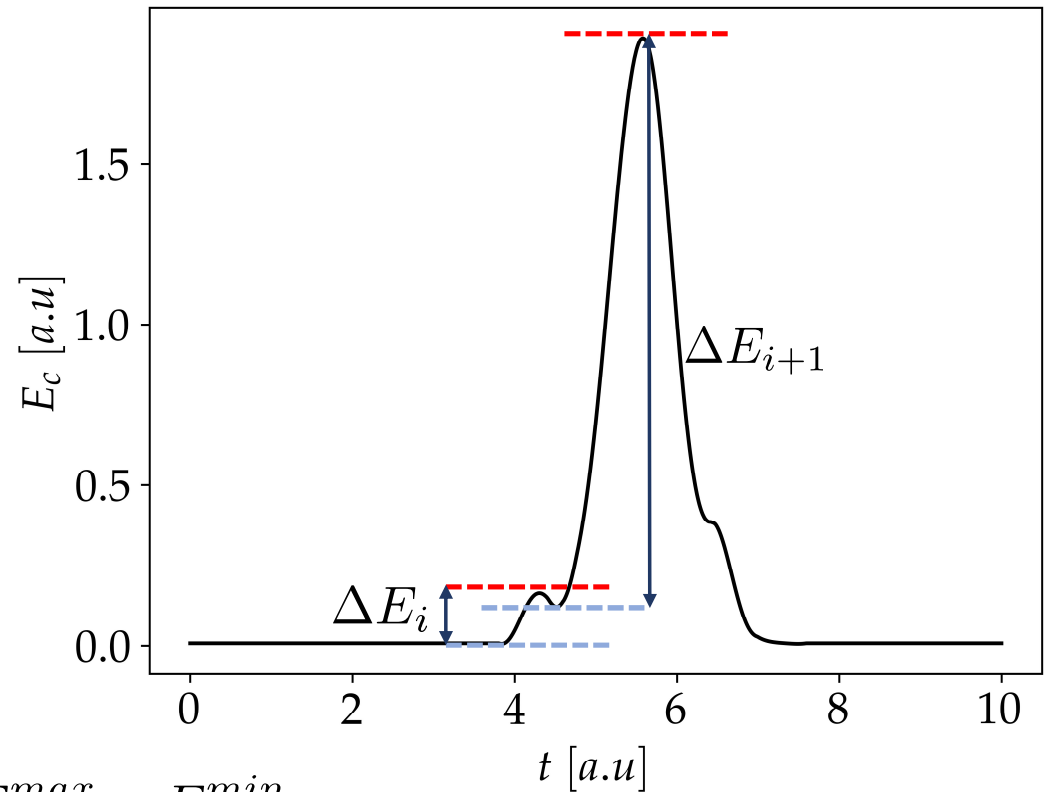
→ E_i^{min}

- Identification of the first local maximum after the i -th minimum in the kinetic energy

→ E_i^{max}

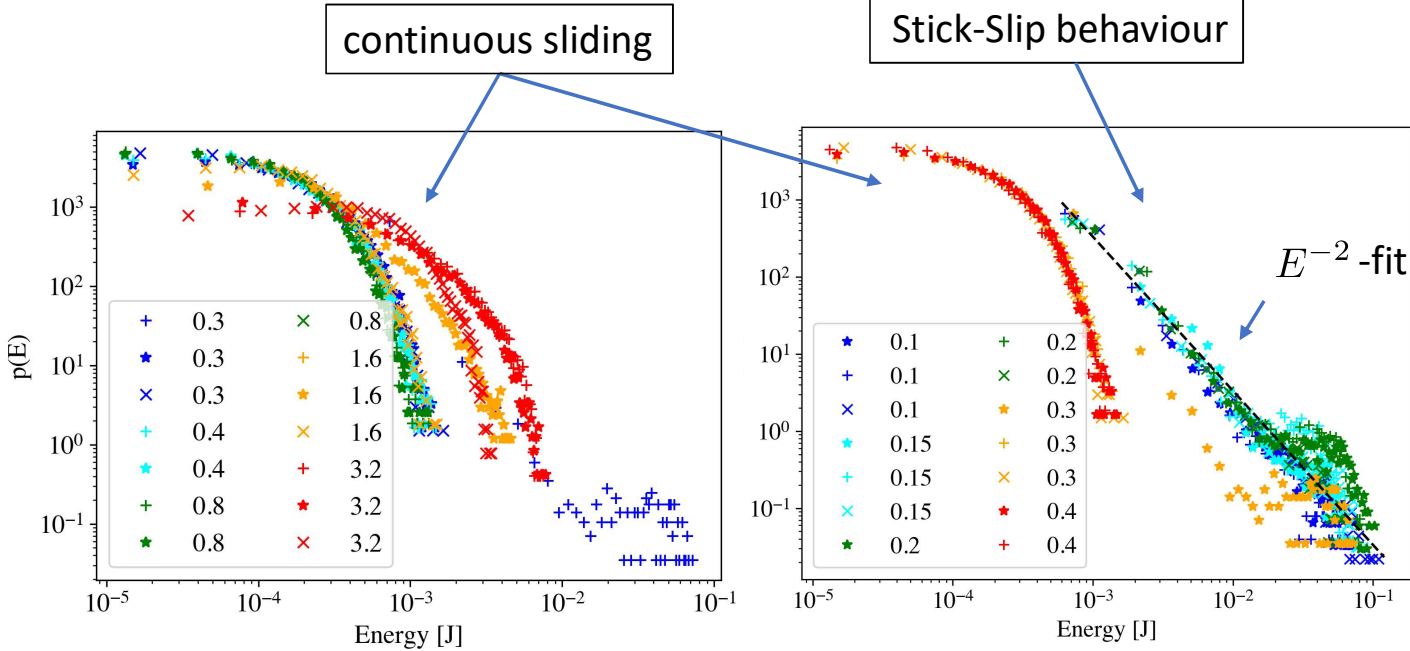
- The energy assigned to the avalanche

→ $\Delta E_i = E_i^{max} - E_i^{min}$

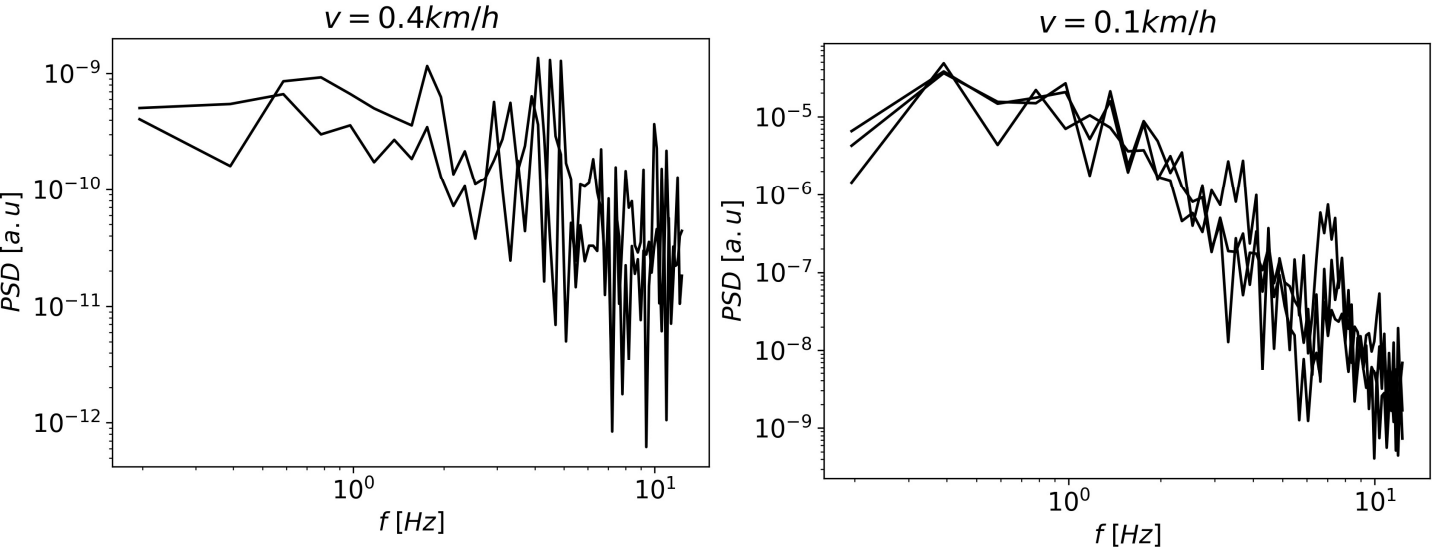


Experimental results

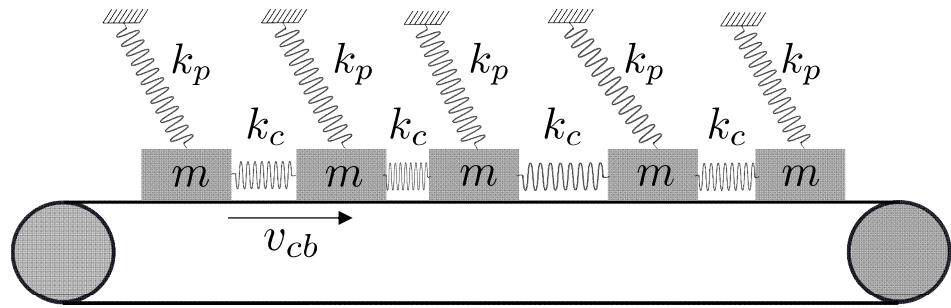
Avalanche statistics



Power spectral density from $E_c(t)$



dynamical model



The spring force acting on the blocks

$$f_s = \begin{cases} i = 0 & : -k_p \cdot x_i + k_c \cdot (x_{i+1} - x_i) \\ i = \overline{1, N-1} & : -k_p \cdot x_i + k_c \cdot (x_{i+1} - 2 \cdot x_i + x_{i-1}) \\ i = N & : -k_p \cdot x_i + k_c \cdot (x_{i-1} - x_i) \end{cases}$$

- k_p → pooling spring spring constant
- k_c → coupling spring spring constant
- m → mass of bodies
- F_c → static friction force
- $F_c \cdot \alpha$ → dynamic friction force
- v_{rstick} → maximum relative speed for sticking

Total resultant force acting on the blocks

$$f_i = \begin{cases} |f_s| > F_c & : f_s - \text{sign}(\dot{x}_i - v_{cb}) \cdot F_c \cdot \alpha \\ \dot{x}_i - v_{cb} = 0 \text{ and } |f_s| \leq F_c & : 0 \\ |\dot{x}_i - v_{cb}| > v_{rstick} \text{ and } |f_s| \leq F_c & : f_s - \text{sign}(\dot{x}_i - v_{cb}) \cdot F_c \cdot \alpha \\ |\dot{x}_i - v_{cb}| < v_{rstick} \text{ and } |f_s| \leq F_c \text{ and } \text{sign}(\dot{x}_i - v_{cb}) = \text{sign}(f_s) & : \\ & f_s - \text{sign}(\dot{x}_i - v_{cb}) \cdot F_c \cdot \alpha \\ |\dot{x}_i - v_{cb}| < v_{rstick} \text{ and } |f_s| \leq F_c \text{ and } \text{sign}(\dot{x}_i - v_{cb}) \neq \text{sign}(f_s) & : \\ & 0 \text{ (and } \dot{x}_i \rightarrow v_{cb}) \end{cases}$$

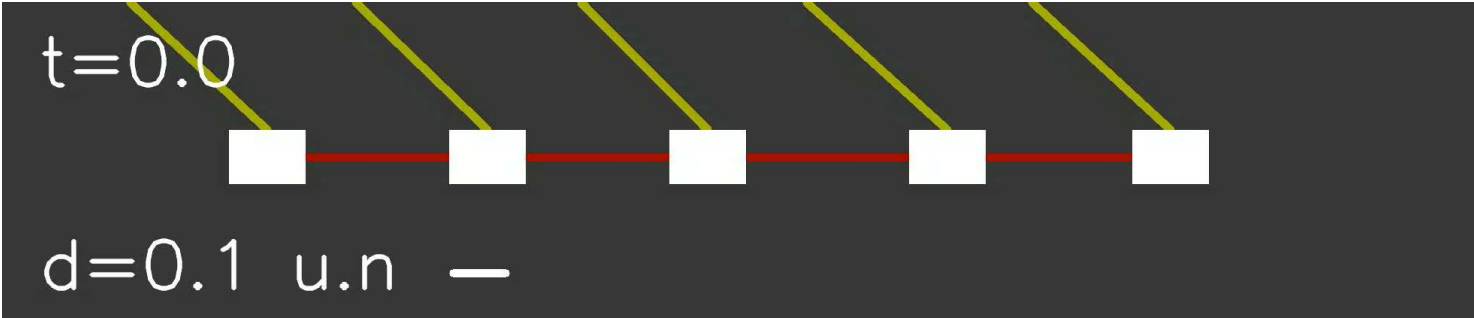
$$\ddot{x}_i \cdot m = f_i$$

Numerical implementation

- The simulations were performed in C++.
- The equations of motion were integrated using the 4 order Runge Kutta method
- The experimentally obtained Stick-Slip and periodic behaviors were successfully reproduced

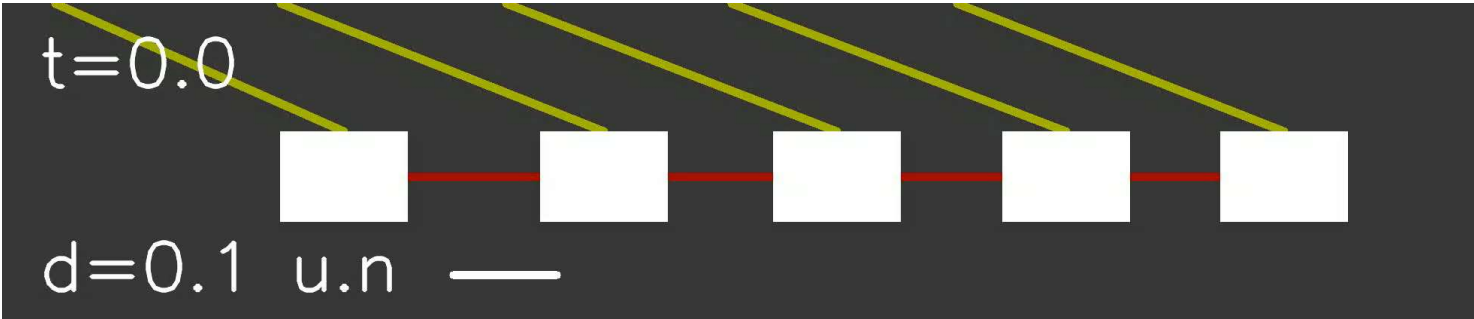
Stick-Slip behavior

$\alpha = 0.4, v_{cb} = 0.02$

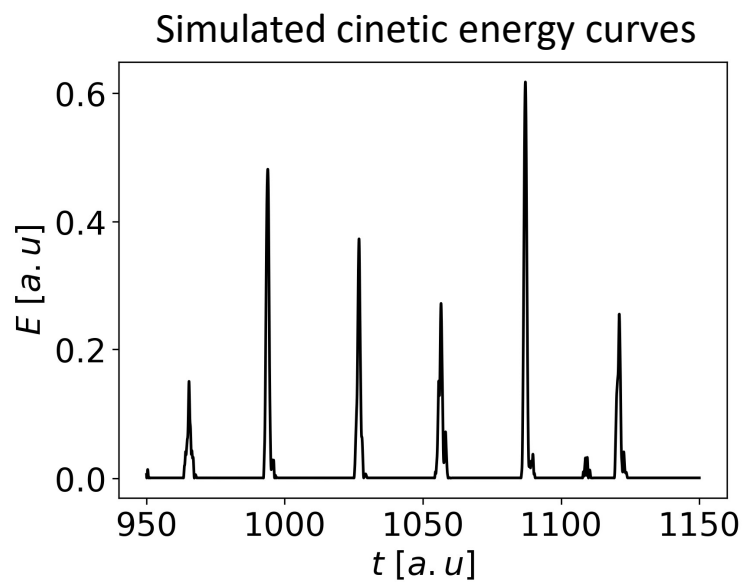


periodic behavior

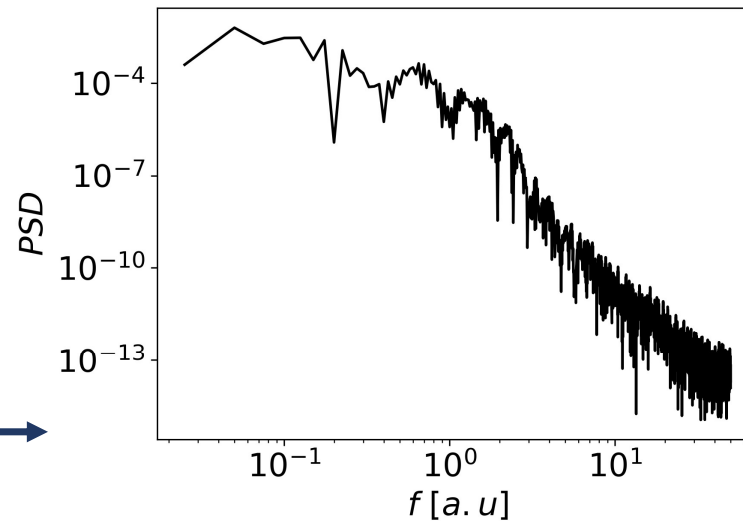
$\alpha = 0.5, v_{cb} = 0.05$



Stick-Slip behavior
 $\alpha = 0.2307, v_{cb} = 0.02$

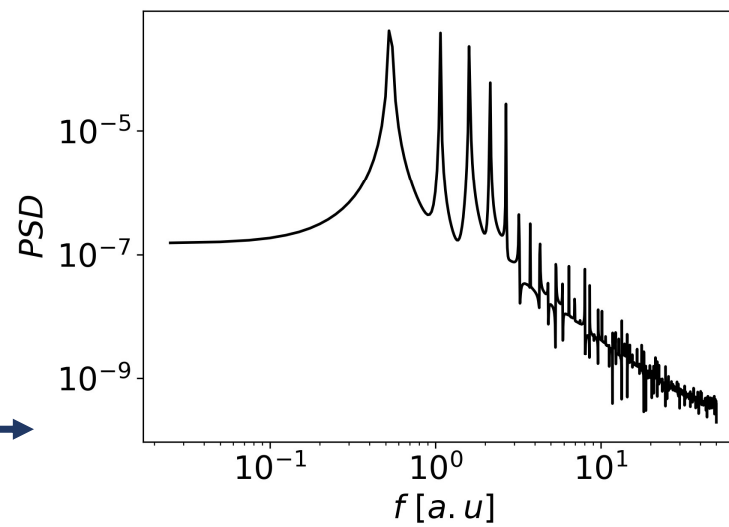
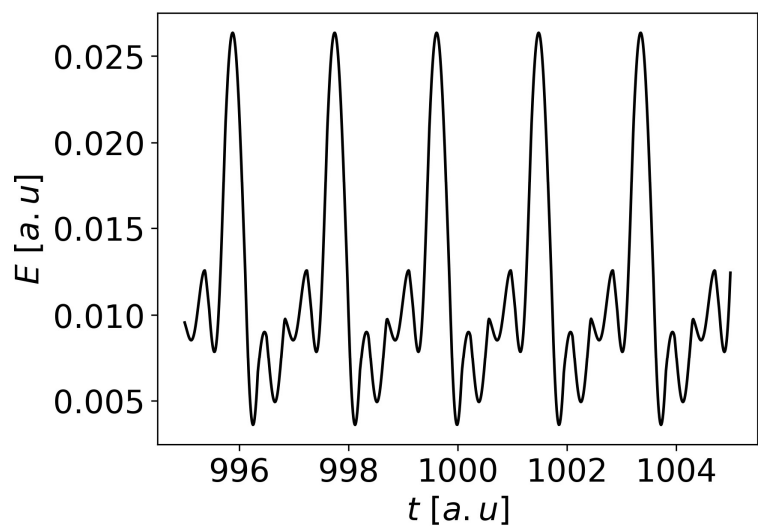


energy curves power spectra



$N_{body} = 5, dt = 5 \cdot 10^{-4}$
 $v_{rstick} = 5 \cdot 10^{-5}, F_c = 1$
 $k_p = 1.6, k_c = 11$

periodic behavior
 $\alpha = 0.5, v_{cb} = 0.04$



spectral entropy

Spectral entropy (SE) is the Shannon entropy of the normalized power spectral density (PSD) of the time series :

$$P(f) = \frac{PSD(f)}{\sum_{f=0}^{f_s/2} PSD(f)}$$

f_s → sampling frequency

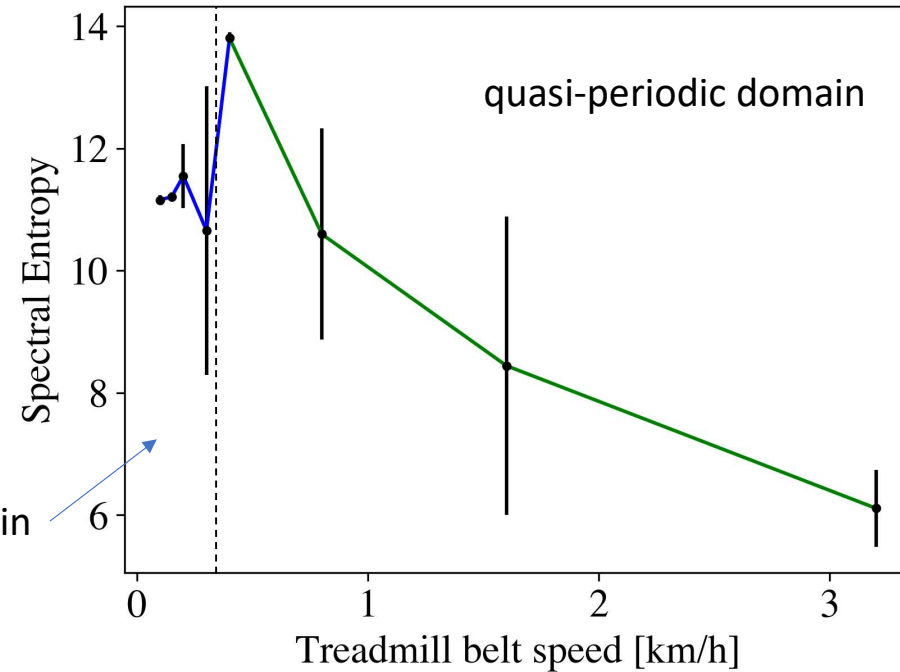
$$SE(f_s) = - \sum_{f=0}^{f_s/2} P(f) \cdot \log_2[P(f)]$$

Stick-Slip domain

The spectral entropy was used to characterize the periodicity of the time series

Low SE → periodic behaviour

spectral entropy calculated for experiments

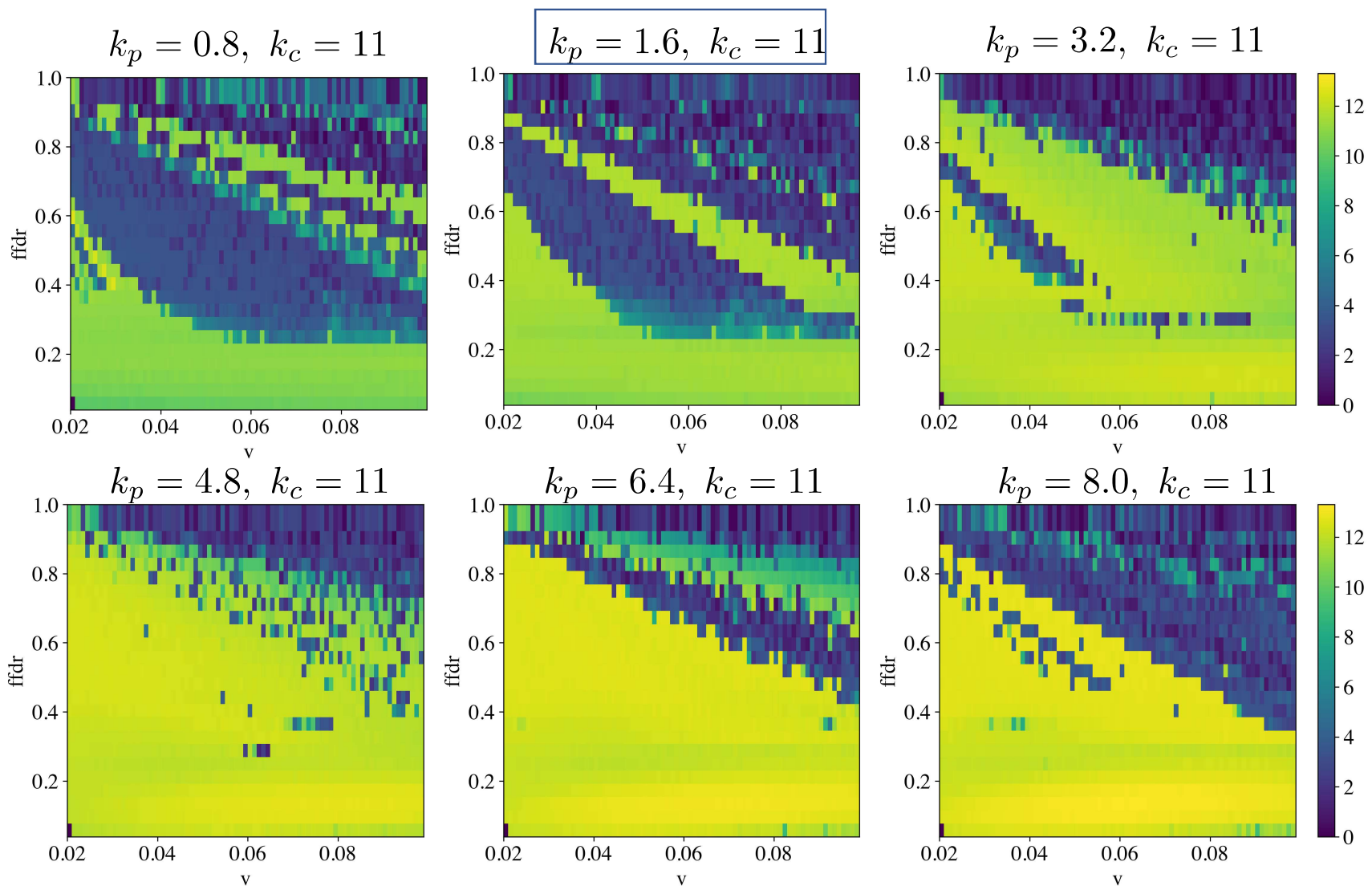


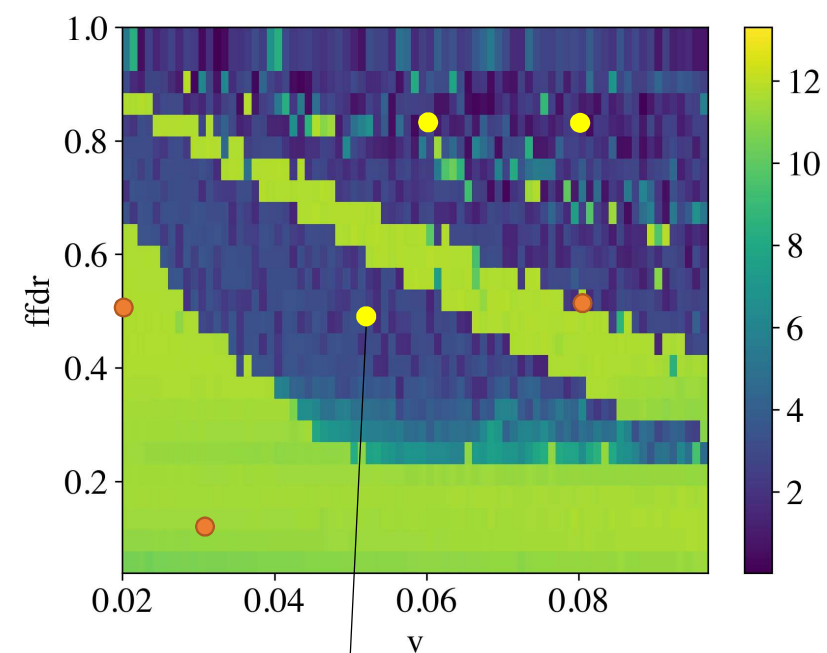
Spectral Entropy

$$N_{body} = 5, dt = 5 \cdot 10^{-4}$$
$$v_{rstick} = 5 \cdot 10^{-5}, F_c = 1$$

Periodic behavior ->
low spectral entropy

Stick-Slip behaviour ->
high spectral entropy

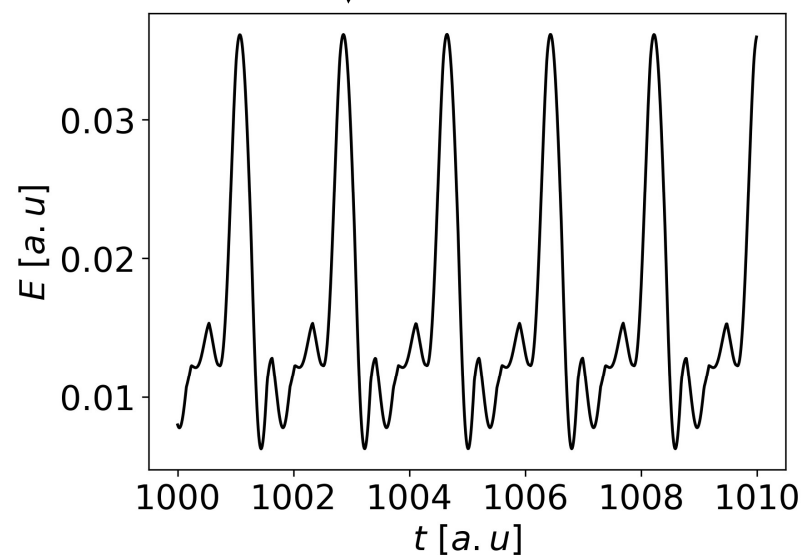
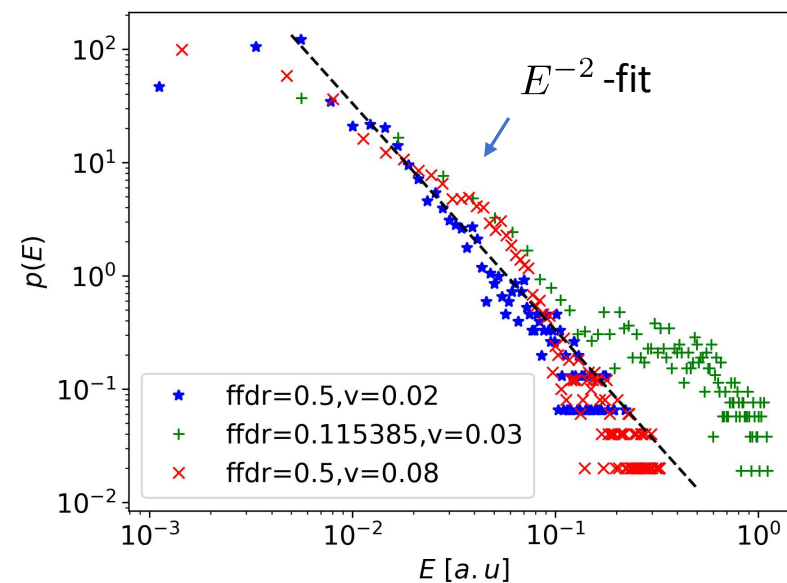




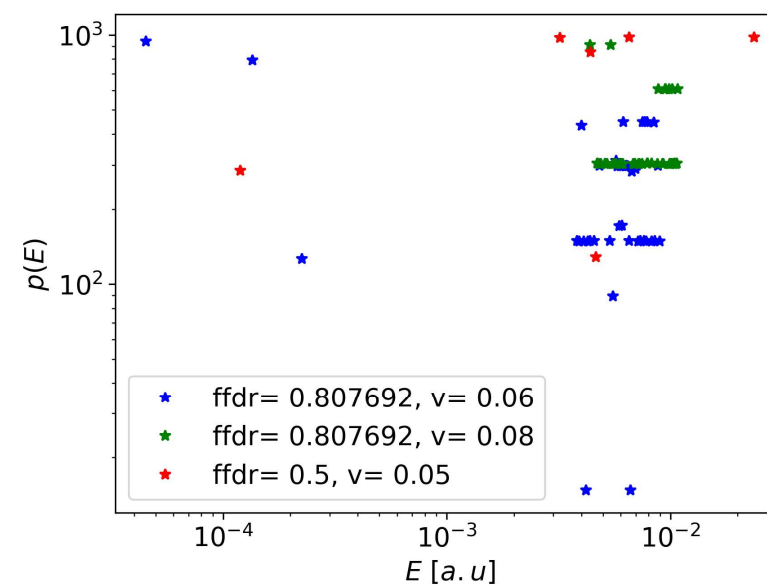
$$N_{body} = 5, dt = 5 \cdot 10^{-4}$$

$$v_{rstick} = 5 \cdot 10^{-5}, F_c = 1$$

Similar behavior in the
Stic-Slip domain



Behavior different from
experiments in the periodic
domain

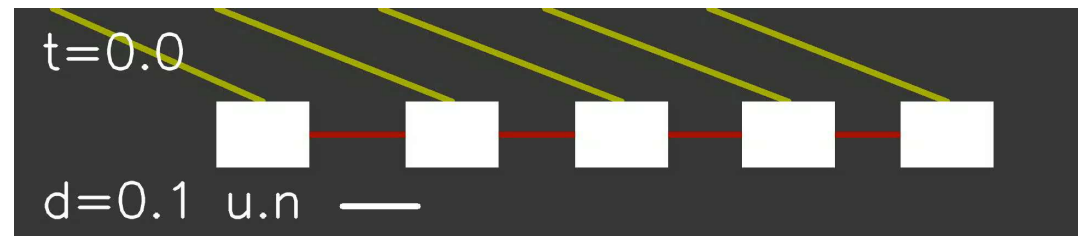


Conclusions

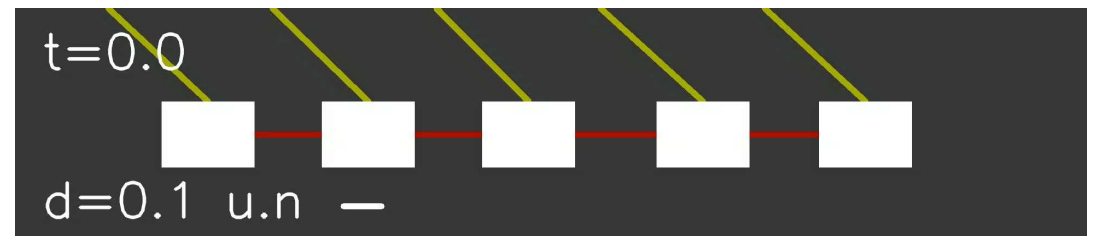
- simple experimental realization of the Burridge-Knopoff type spring-block model by using a spring-block chain on a treadmill
- The experiments show qualitatively different behavior in different speed regimes
- Power-law type scaling for the avalanche size distribution as a function of avalanche energy
- The simple computer model reproduces the main features of the observed dynamics
- Similar avalanche size scaling to the one observed for earthquakes

Numerical implementation

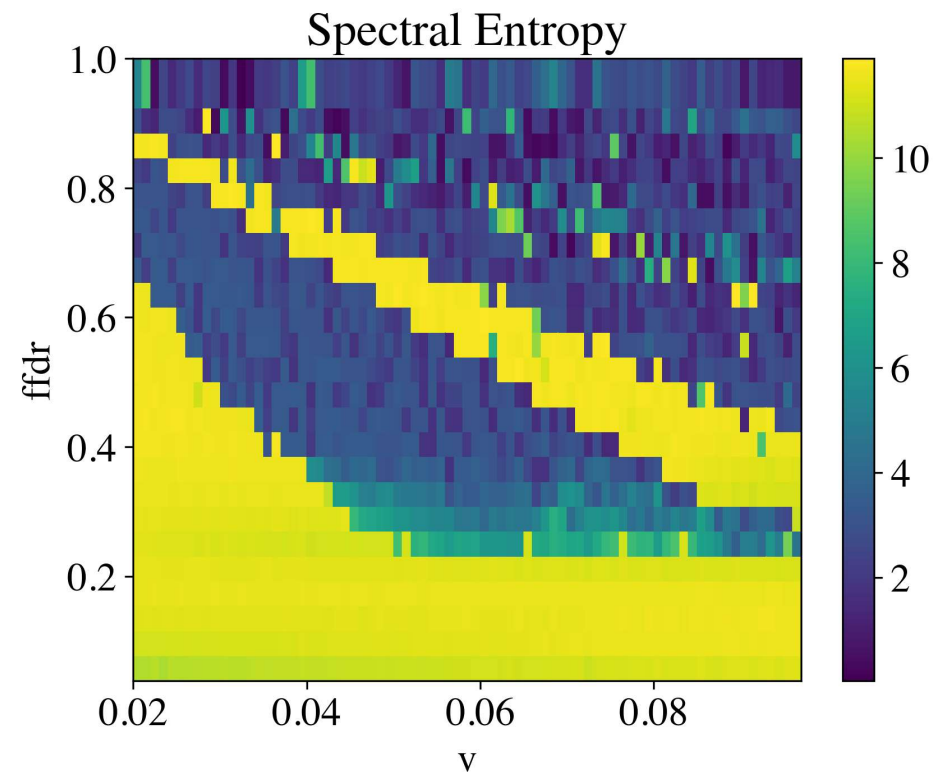
periodic behavior



Stick-Slip behavior



Numerical results



videok

